

Features

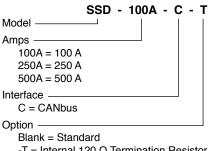
- Formerly a Riedon[™] product
- 24-bit isolated shunt current sensor with CANbus interface
- 100 A (2 kA peak), 250 A (5 kA peak), or 500 A (10 kA peak)
- Dielectric withstand: 1500 VDC
- Reinforced insulation according to IEC 60664
- 16-bit +150 °C microcontroller
- 24-bit ADC with buffered analog inputs
- ECC flash memory with autocorrect single bit errors
- Internal and external CRC data error detection
- Advanced non-linear temperature compensation
- RoHS compliant*

SSD Series – Riedon™ Digital Current Sensor with CANbus Interface by Bourns

Specifications

Characteristic	SSD-100A	SSD-250A	SSD-500A			
Nominal Current (A)	±100	±250	±500			
Peak Current (No Clipping)	+2 kA / -1 kA	+5 kA / -2.5 kA	+10 kA / -5 kA			
Shunt Resistance ($\mu\Omega$) Excluding primary termination resistance	300	120	60			
Initial Accuracy		< ±0.1 %				
Linearity Over Current Range	< ±0.1 % + 5 mA	< ±0.1 % + 13 mA	< ±0.1 % + 25 mA			
Bandwidth		5 kHz				
ADC Resolution		24 bits				
Speed (readings per second)	up to 1100 rps (0.9 - 3300 ms per reading)					
Supply Voltage (5 - 60 VDC)	@ 5.0 V, 55	5 mA typical	@ 24 V, 15 mA typical			
DC Bus Voltage Range	±1.	200 VDC max. (10 M input impedan	ce)			
Linearity Over Voltage Range		< ±0.1 % + 25 mV				
CAN Interface	CAN 2.0 A S	Speeds: 125 K, 250 K, 500 K (defau	lt), 1 M baud			
Long Term Stability		% 1000 hours 60 °C terminal tempe % 1000 hours 115 °C terminal temp				
Galvanic Isolation	1500 VDC 1000	VAC RMS (maximum continuous v	vorking voltage)			
Dielectric Strength	3500 VAC RMS 1 minute					
Operating Temperature	-40 °C to +115 °C ambient -40 °C to +125 °C primary conductor (see derating curve on page 2)					
Storage Temperature		-55 °C to +125 °C				

How to Order



-T = Internal 120 Ω Termination Resistor

Materials (RoHS Compliant)

Resistance Element.....CuMnNi Current Terminal¹.... Nickel-plated copper Electronics Housing......94-V0 rated Note:

1 Suitable for copper, copper-clad aluminum or aluminum conductors

Additional Information

Click these links for more information:



Product Safety Notice

The SSD Series Digital Current Sensor must be used in a manner specified by this data sheet, otherwise the protection provided by the equipment may be impaired. The SSD Series should not be treated as a structural part of the installation and must be properly supported on both ends.



*RoHS Directive 2015/863, Mar 31, 2015 and Annex.

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Applications

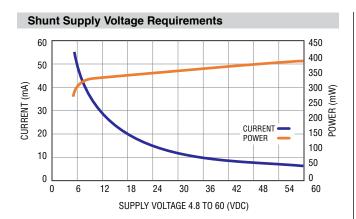
- EV charging stations
- Battery systems
- Renewable energy
- Motor drives

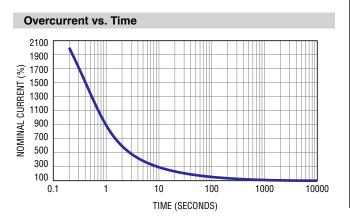
SSD Series – Riedon™ Digital Current Sensor with CANbus Interface by Bourns

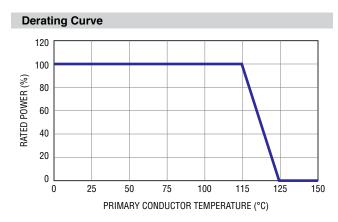
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Specifications (continued)

Madal	Typical Noise (mA RMS) per ADC Reading Interval (ms), 1.25X Range, Zero						Zero C	urrent								
Model	0.9	1.6	3.2	4.8	6.4	7.2	9	13	26	51	102	205	410	820	1640	3280
SSD-100A	3	3	2	2	2	2	1	1	1	1	1	<1	<1	<1	<1	<1
SSD-250A	8	7	6	5	5	4	4	3	3	2	2	1	1	1	<1	<1
SSD-500A	15	13	12	11	10	9	7	7	5	4	3	2	2	1	1	1







Connectors

SSD Connector	Mating Connector	Molex Nano-Fit Part Number
4-Pin Male	4-Pin Female	1053071204
	0-22 AWG Female Contacts*	1053002200
	4-Pin TPA Strain Relief	1053251004
	2-Pin Female	1053071202
2-Pin Male Vbus	20-22 AWG Female Contacts*	1053002200
	2-Pin TPA Strain Relief	1053251002

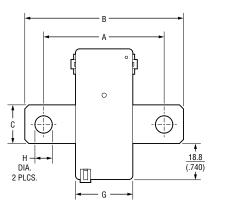
* Use Gold (Au) plated contacts for 115 °C temperature rating.

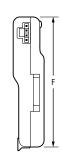
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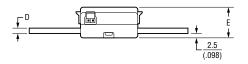
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Product Dimensions







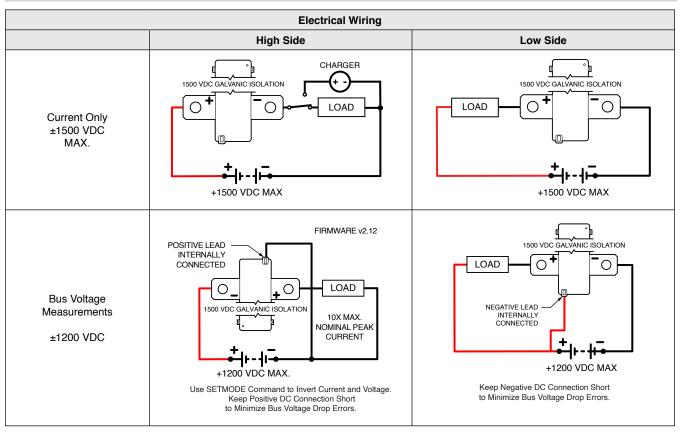
Model	SSD-100A	SSD-500A					
A		$\frac{63.5 \pm 0.5}{(2.50 \pm .020)}$					
В		$\frac{84 \pm 0.5}{(3.307 \pm .020)}$					
С		$\frac{20 \pm 0.5}{(.787 \pm .020)}$					
D		$\frac{3 \pm 0.5}{(.118 \pm .020)}$					
E	<u>16.4</u> (.646 =	± 0.5 ± .020)	$\frac{17.4 \pm 0.5}{(.685 \pm .020)}$				
F		$\frac{68.8 \pm 0.5}{(2.709 \pm .020)}$					
G		$\frac{30.8 \pm 0.5}{(1.213 \pm .020)}$					
Н		$\frac{8.7 \pm 0.5}{(.343 \pm .020)}$					

MM (INCHES) DIMENSIONS:

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Installation



Specifications are subject to change without notice.

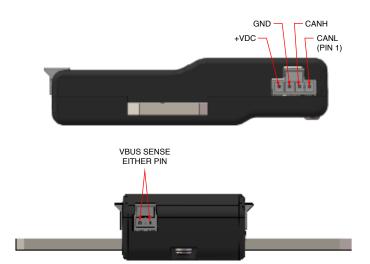
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Connectors

Connectors on both sides have same pinout. Either or both connectors can be used.

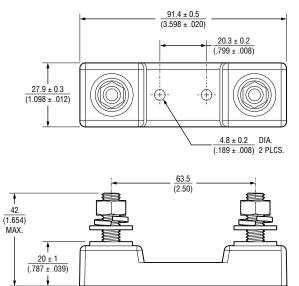
CANbus



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Optional Base Mounting Fixtures

SSA-BASE



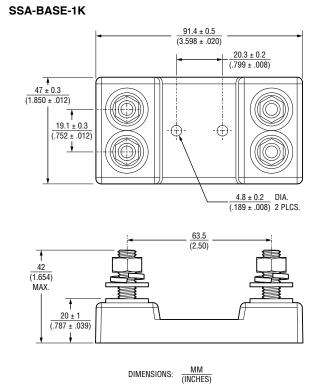
DIMENSIONS: MM (INCHES)



Optional SS-CABLE Power / Serial Connection SS-CABLE-1M



Serial Output					
White	CANL / 485A	Pin 1			
Yellow	CANH / 485B	Pin 2			
Black	Ground	Pin 3			
Red	+5 to 60 VDC	Pin 4			



- Robust design
- 5/16-18 Stainless Steel Hardware
- Torque Nuts:
- 11-13 ft-lb (15-17.6 N-m)
- UL 94-V0 rated materials



- For all SSD models
- Color-coded 22 ga wire
- Two twisted pairs
- 1 meter standard length

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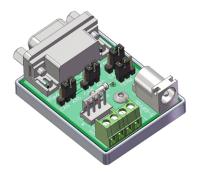
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Optional SSD Connector Sets SSD-CONN-SET

Standard Connector Set						
Includes	Molex P/N	Description				
1 pc.	1053071204	4-Pin Female				
1 pc.	1053071202	2-Pin Female				
6 pcs.	1053002200	20-22 AWG Female Crimp Terminals				
1 pc.	1053251004	4-Pin TPA				
1 pc.	1053251002	2-Pin TPA				

Optional SSD Serial Connection Kit SSD-SERKIT



Serial Connection Kit					
Includes	Description				
1 pc.	SSD to DB-9F Serial Adapter				
1 pc.	5 VDC USB Power Cable				
1 pc.	4-Pin Programming Cable (1 m Length)				

The SSD serial connection kit simplifies the initial setup of the SSD Series Digital Current Sensor. It includes the necessary components to connect USB to CAN and USB to RS-485 serial adapters that have a 9-pin DB-9 male output connector. It includes jumpers to switch from RS-485 to CANbus and enable a termination resistor. USB to serial adapter not included.

USB to RS-485 Adapter - From DTEK, StarTech and others with RS-485 on DB9 pins 1 and 2 and the ground on pin 5. Note: Some adapters have the 485A and 485B pins reversed.

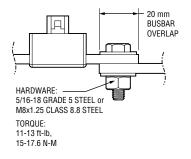
USB to CANbus adapter - From PEAK, Kvaser and others with CAN on DB9 pins 2 and 7 and the ground on pin 3.

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Frequently Asked Questions

- Q: Is it necessary to install the SSD Series on the low side of the circuit?
- A: The SSD Series Digital Current Sensors is completely isolated, so it may be installed in either the low or high side of the circuit.
- Q: The sensor is only sending whole Coulombs and Watthours, how precise are these?
- A: Internally, micro-coulombs and micro-joules are counted; so very short ADC timing intervals and very low currents are accurately counted.
- Q: What is the best way to connect to the SSD Series terminals?
- A: Make sure connections are clean and well prepared. Bolts to be torqued to the hardware manufacturer's recommendations. There should be sufficient clamping force to ensure proper connection. Overlap shown below should be taken as a minimum. Suitable for Copper, Copper-Clad Aluminum or Aluminum conductors.



Q: What size wire is suitable for the SSD Series?

A:

Q: What is the best way to cool the SSD Series Digital Current Sensor?

- A: A majority of the heat generated by the SSD Series is dissipated through the primary conductors. Care should be taken to ensure that the primary conductors are sized appropriately given expected amperage and conductor length. Bourns recommends a 115 °C maximum conductor temperature at rated current. If there are thermal concerns, oversizing the conductors will help minimize the operating temperature of the Digital Current Sensor.
- Q: When should I use the SSD version with the internal 120 Ω termination resistor (-T)?
- **A:** The -T version includes a built-in 120 Ω resistor between CANH/CANL or 485A/485B. Typical RS485 or CANbus networks require termination at two endpoints. Use the -T version accordingly. Avoid using more than two termination points to ensure proper communication.

	Copper Conductor Ampacity Ratings (continuous)								
mm²	AWG	Amps (75 °C)	mm²	AWG	Amps (75 °C)				
13.3	6	65	107	0000 (4/0)	230				
21.2	4	85	127	250 MCM	255				
33.6	2	115	152	300 MCM	285				
42.4	1	130	203	400 MCM	335				
54	0 (1/0)	150	253	500 MCM	380				
67	00 (2/0)	175	380	750 MCM	475				
85	000 (3/0)	200	887	1500 MCM	625				

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SSD Interface Manual

SSD CAN IDs for Settings (Defau	ults)					
SET COMMAND ID	0x3FA					
GET COMMAND ID	0x3FB					
REPLY ID	0x3FC					
CAN IDs for Sensor Readings (Defaults)						

CURRENT0x3F1TEMPERATURE0x3F2VBUS0x3F3COULOMB0x3F4POWER0x3F5ENERGY0x3F6ERRORS/ALERT0x3F7

Motorola Intel Intel Intel Intel Intel Intel

Intel

Motorola

Motorola

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Default Baud 500 kbp/s Used to Write values Used to Read values Returned Data from Get Command

Sensor Current Sensor Temperature Bus Voltage Coulomb Counter Power Energy Counter Errors or Alerts

Intel (Data Byte 0 = LSB) data format for Sensor Readings Motorola (Data Byte 0 = MSB) data format for all Settings to improve legibility with setup

Name	Size	Units	Range	Format	
Current	Signed int32	1 mA	± 20 X Nominal	Intel	
Temperature	Signed int32	0.1 °C	-40 °C to +125 °C*	Intel	
Bus Voltage (Vbus)	Signed int32	1 mV	± 1200 V _{DC}	Intel	
Coulomb	Signed int64	1C (A•s)	± 2 ⁶⁰	Intel	
Power	Unsigned int32	0.1 W	0 to 2 ³²	Intel	
Energy	Unsigned int64	W•h	0 to 260	Intel	

COMMAND LIST

GET ALL ENABLED	0x00 - Read Only	VBUS UNDER LIMIT	0x1B
GET CURRENT	0x01 - Read Only	VBUS OVER LIMIT	0x1C
	, <u>,</u>		
GET TEMPERATURE	0x02 - Read Only	POWER OVER LIMIT	0x1D
GET VBUS	0x03 - Read Only	SHUNT NANO-OHM	0x1E
GET COULOMB	0x04 - Read Only	CURRENT ZERO OFFSET	0x21
GET POWER	0x05 - Read Only	VBUS FACTOR	0x22
GET ENERGY	0x06 - Read Only	VBUS ZERO OFFSET	0x23
GET ERRORS	0x07 - Read Only	TEMP OFFSET	0x24
RESET COMMAND	0x10 - Write Only	T0 TEMP COMPENSATION	0x25 - Read Only
SET CAN IDS	0x11 - Write Only	T1 TEMP COMPENSATION	0x26 - Read Only
SETMODE	0x12	T2 TEMP COMPENSATION	0x27 - Read Only
BAUDRATE	0x14	RESET CAUSES	0x28 - Read Only
READING DELAY	0x16	FIRMWARE VERSION	0x30 - Read Only
A2D CONFIG	0x17	SERIAL NUMBER	0x31 - Read Only
CURRENT UNDER LIMIT	0x18		
CURRENT OVER LIMIT	0x19		
TEMP OVER LIMIT	0x1A		

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SSD Interface Manual (continued)

0x00 - Command GET ALL ENABLED - Read Only

Used to get all enabled readings in the SETMODE command. Current, Temperature, Vbus, etc...

	Message ID	Length	Data Fields (LSB First)						
SEND	0x3FB	0x01	0x00						
RECEIVE	Multiple replies from all enabled readings in the SETMODE Command								

0x01 - Command GET CURRENT - Read Only

Used to get the last sensor current reading in milliamps.

Reply is 4 bytes from CAN ID 0x3F1 (default) - Intel Format (Data Byte 0 = LSB)

	Message ID	Length	Data Fields (LSB First)								
SEND	0x3FB	0x01	0x01								
RECEIVE	0x3F1	0x04	0xXX	0xXX	0xXX	0xXX					

0x02 - Command GET TEMPERATURE - Read Only

Used to get the last sensor temperature reading in 0.1 centigrade.

Reply is 4 bytes from CAN ID 0x3F2 (default) - Intel Format (Data Byte 0 = LSB)

	Message ID	Length	Data Fields (LSB First)								
SEND	0x3FB	0x01	0x02								
RECEIVE	0x3F2	0x04	0xXX	0xXX	0xXX	0xXX					

0x03 - Command GET VBUS - Read Only

Used to get the last external bus voltage reading in milli-Volts.

Reply is 4 bytes from CAN ID 0x3F3 (default) - Intel Format (Data Byte 0 = LSB)

	Message ID	Length	Data Fields (LSB First)								
SEND	0x3FB	0x01	0x03								
RECEIVE	0x3F3	0x04	0xXX	0xXX	0xXX	0xXX					

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SSD Interface Manual (continued)

0x04 - Command GET COULOMB - Read / Write

Used to get or set the last coulomb count which is continuously updated with current.

Note: The coulomb reading can overflow! It is up to the user to check if very large values (> $\pm 2^{60}$) are expected. See 0x07 command to read overflow bit.

Reply is 8 bytes from CAN ID 0x3F4 (default) - Intel Format (Data Byte 0 = LSB) Note: Writing a new value is limited to signed int32 values. Example: Write 500,000 (0x7A120) to coulomb counter

Write Message

	Message ID	Length	Data Fields										
SEND	0x3FA	0x05	0x04	0x00	0x07	0xA1	0x20						
RECEIVE		(none)											

Read Message

	Message ID	Length	Data Fields (LSB First)									
SEND	0x3FB	0x01	0x04									
RECEIVE (int64)	0x3F4	0x08	0xXX	0xXX	0xXX	0xXX	0xXX	0xXX	0xXX	0xXX		

0x05 – Command GET POWER – Read Only

Used to get the last power reading in 0.1 watts.

Reply is 4 bytes from CAN ID 0x3F5 (default) - Intel Format (Data Byte 0 = LSB)

	Message ID	Length		Data Fields (LSB First)								
SEND	0x3FB	0x01	0x05									
RECEIVE	0x3F5	0x04	0xXX	0xXX	0xXX	0xXX						

0x06 - Command GET ENERGY - Read Only

Used to get the last energy count in Watt-hours (Wh) which is continuously updated.

Note: The energy reading can overflow! It is up to the user to check if very large values (> 260) are expected. See 0x07 command to read overflow bit.

Reply is 8 bytes from CAN ID 0x3F6 (default) - Intel Format (Data Byte 0 = LSB)

	Message ID	Length	Data Fields (LSB First)									
SEND	0x3FB	0x01	0x06									
RECEIVE (int64)	0x3F6	0x08	0xXX	0xXX	0xXX	0xXX	0xXX	0xXX	0xXX	0xXX		

Specifications are subject to change without notice.

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SSD Interface Manual (continued)

0x07 - Command GET ERRORS/Alerts - Read Only

Used to get any errors or alerts which are continuously updated. Reply is 2 bytes from CAN ID 0x3F7 (default) - Intel Format (Data Byte 0 = LSB)

	Message ID	Length	Data Fields (LSB First)								
SEND	0x3FB	0x01	0x07								
RECEIVE	0x3F7	0x02	0xXX	0xXX							

	Returned ERROR / ALERT bits														
15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
N/A	1 = ECC Single Bit	1 = EEPROM Corrupt	1 = EEPROM R/W	1 = ADC Initialization	1 = ADC CRC Read	1 = Energy Overflow	1 = Coulomb Overflow	1 = Power Over Limit	1 = Vbus Over Limit	1 = Vbus Under Limit	1 = Temp Over Limit	1 = Current Over Limit	1 = Current Under Limit	1 = Current Range Over	1 = Vbus Range Over

Bit0 Vbus Range Over - Bus Voltage exceeds the MAX voltage for the range selected, see 0X17 command.

Bit1 Current Range Over - Peak current exceeded the range selected, see 0X17 command.

Bit2 Current Under Limit - Current is below the limit set, see 0X18 command.

Bit3 Current Over Limit - Current is above the limit set, see 0X19 command.

Bit4 Temp Over Limit - Temperature is above +125 °C or the limit set, see 0X1A command.

Bit5 Vbus Under Limit – Bus Voltage is below the limit set, see **0X1B** command.

Bit6 Vbus Over Limit - Bus Voltage is above the limit set, see **0X1C** command.

Bit7 Power Over Limit – Power is above the limit set, see **0X1D** command.

Bit8 Coulomb Overflow – Coulombs have exceeded the range of $\pm 2^{47}$.

Bit9 Energy Overflow - Energy has exceeded 248.

Bit10 ADC CRC Read - The ADC's CRC doesn't match the calculated CRC of the returned data.

Bit11 ADC Initialization - The ADC's initialized registers don't match the written values.

Bit12 EEPROM R/W - Error reading or writing to the internal EEPROM.

Bit13 EEPROM Corrupt - The EEPROM CRC doesn't match saved value.

Bit14 ECC Single Bit Error - Flash Memory had an Auto-Correctable Error.

Users should verify actual device performance in their specific applications.

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SSD Interface Manual (continued)

0x10 - Command RESET COMMAND - Write Only

Rebooting will restore previously saved settings if current settings are not saved. This will prevent baud rate or address errors since you will need to connect with the new values before you can issue the save to EEPROM command.

0x0001 – Reset Coulomb and Energy counters 0x0004 – Reset Errors 0x000F – Save settings to EEPROM 0X00AA – Reset settings to defaults (command must be sent 3X in a row)

Example: To save settings to EEPROM

	Message ID	Length			Data	Fields	
SEND	0x3FA	0x03	0x10	0x00	0x0F		
RECEIVE				(none)			

0x11 - Command SET IDs - Write Only

Used to change the default SSD CAN bus IDs to different ID numbers.

Example: To change the default CURRENT CAN ID from 0x03F1 (1009) to 0x04B0 (1200)

	Message ID	Length			Data	Fields		
SEND	0x3FA	0x05	0x11	0x03	0xF1	0x04	0xB0	
RECEIVE				(none)				

NOTE: No settings are saved until a save settings to EEPROM command is issued! Power cycling will restore previous settings. See command 0x10 0x000F.

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SSD Interface Manual (continued)

0x12 - Command SETMODE - Read / Write

Used to change the sensor options.

Bit0 Invert Current – This will flip the Current and Coulomb signs if necessary.

Bit1 Autorange – Sensor will switch to high range if reading exceeds 85 % of standard range. It will switch back when reading drops to below 50 % of standard range. See A2D CONFIG for more info.

Bit2 Modbus Enable - Not used on CANbus version.

Bit3 Auto Reset Errors - Self clears errors once sent or read, the error will re-enable if it persists.

Bit4 Invert Voltage - Use for Highside Voltage Measurements.

Bit7 Send on Conversion – The sensor will send the latest data as soon as available per A2D CONFIG.

Bit8 Autosend – The sensor will send readings at the Read Delay timer interval unless Bit7 is enabled.

Bit9 to Bit15 – Enable the readings to be automatically sent. Otherwise read them manually.

	SETMODE Configuration Bytes														
HEXCODE: 0000 Check boxes below to calculate HEX value															
15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0
1 = Send Errors/Alerts	1 = Send Energy Cnt	1 = Send Power	1 = Send Coulomb Cnt	1 = Send Vbus	1 = Send Temperature	1 = Send Current	1 = Autosend	1 = Send on Conversion	N/A	N/A	1 = Invert Voltage	1 = Auto Reset Errors/Alerts	Reserved	1 = Autorange	1 = Invert Current

NOTE: No settings are saved until a save settings to EEPROM command is issued! Power cycling will restore previous settings. See command 0x10 0x000F.

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SSD Interface Manual (continued)

0x12 (Continued) - Command SETMODE - Read / Write SETMODE default is: 0x0002. Example: To enable Autosend, Send Current, Send Errors, Auto Reset Errors (0x8308)

Write Message

	Message ID	Length	Data Fields							
SEND	0x3FA	0x03	0x12	0x83	0x08					
RECEIVE	(none)									

Read Message

	Message ID	Length	Data Fields						
SEND	0x3FB	0x01	0x12						
RECEIVE	0x3FC	0x03	0x12	0x83	0x08				

NOTE: No settings are saved until a save settings to EEPROM command is issued! Power cycling will restore previous settings. See command 0x10 0x000F.

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SSD Interface Manual (continued)

0x14 - Command BAUD RATE - Read / Write

Used to set the SSD CAN bus Baud Rate. Values other than the following are ignored.

HEX Value	Baud Rate (kbit/s)
0x0009	125
0x000A	250
0x000B	500
0x000C	1000

Notes: Baud rate is changed immediately so you may get an error after change. Connect using new baud rate and use Command RESET MODE (0x10 0x000F) to save current settings to EEPROM. If unable to connect, reboot to restore the previous setting. BAUD RATE is defaulted to: 0x000B (500 kb/s).

Example: To set Baud Rate to 250 kbps

Write Message

	Message ID	Length	Data Fields							
SEND	0x3FA	0x03	0x14	0x00	0x0A					
RECEIVE		(none)								

Read Message

	Message ID	Length	Data Fields						
SEND	0x3FB	0x01	0x14						
RECEIVE	0x3FC	0x03	0x14	0x00	0x0A				

NOTE: No settings are saved until a save settings to EEPROM command is issued! Power cycling will restore previous settings. See command 0x10 0x000F.

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SSD Interface Manual (continued)

0x16 - Command SET READING DELAY - Read / Write

Used to set the delay between readings automatically sent to the CANbus. Autosend must be enabled (see SETMODE bit8). Note: If the Conversion Time is greater than the reading delay, the sensor will send the same value until the next set of readings is available. For readings faster than 5 ms use SETMODE Bit7 Send on Conversion. This will send the data as soon as it's available.

Delay value from 5 to 60000 milli-seconds. READING DELAY default is: 0x03E8 (1 s).

Example: To set delay to 1 second between readings, 1 s = 1000 = 0x03E8



Write Message

	Message ID	Length			Data	Fields			
SEND	0x3FA	0x03	0x16	0x03	0xE8				
RECEIVE	(none)								

Read Message

	Message ID	Length	Data Fields							
SEND	0x3FB	0x01	0x16							
RECEIVE	0x3FC	0x03	0x16	0x03	0xE8					

NOTE: No settings are saved until a save settings to EEPROM command is issued! Power cycling will restore previous settings. See command 0x10 0x000F.

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SSD Interface Manual (continued)

0x17 - Command A2D CONFIG - Read / Write

							A2D C	onfigura	ation R	egister						
						Che		EXCOD s below to			value					
N/A		us Volta AX Volta		N/A		gh Ran X Curr	ge	N/A	Nor	mal Ra	nge	Reading Interval			al	
																Time (ms)
15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0	
	0	0	0		0	0	0		0	0	0	0	0	0	0	0.9
	1	200 VD	С		402	X Nomi	nal		40	X Nomi	nal	0	0	0	1	1.6
	0	0	1		0	0	1		0	0	1	0	0	1	0	3.2
		600 VDC)		202	X Nomi	nal	_	20	X Nomi	nal	0	0	1	1	4.8
	0	1	0		0	1	0		0	1	0	0	1	0	0	6.4
		300 VDC)		102	X Nomi	nal		10	X Nomi	nal	0	1	0	1	7.2
	0	1	1		0	1	1		0	1	1	0	1	1	0	9
		150 VDC)		5>	(Nomir	nal		5ک	(Nomir	nal	0	1	1	1	13
	1	0	0		1	0	0		1	0	0	1	0	0	0	26
		75 VDC			2.5	X Nomi	inal		2.5	X Nom	inal	1	0	0	1	51
	1	0	1		1	0	1		1	0	1	1	0	1	0	102
	;	37.5 VD(C		1.25	5X Nom	inal		1.2	5X Nom	ninal	1	0	1	1	205
	1	1	0		1	1	0		1	1	0	1	1	0	0	410
		18.7 VD(C		0.63	3X Nom	inal		0.63	3X Nom	ninal	1	1	0	1	820
	1	1	1		1	1	1		1	1	1	1	1	1	0	1640
	9	9.37 VD(C		0.31	IX Nom	inal		0.3	1X Nom	ninal	1	1	1	1	3280

NOTE: No settings are saved until a save settings to EEPROM command is issued! Power cycling will restore previous settings. See command 0x10 0x000F.

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SSD Interface Manual (continued)

0x17 (Continued) - Command A2D CONFIG - Read / Write

Set the bits required for the application.

Notes:

High Range must be greater than or equal to the Normal Range. If SETMODE Bit1 (Autorange) is not set High Range will be ignored. If it is set, the sensor will automaitcally switch between the two ranges specified when necessary.

Reading intervals 13 ms and below utilize hardware averaging, 26 ms and above start using software averaging with a 13 ms hardware interval time. If it is necessary to capture and report fast current spikes, use fast reading intervals otherwise they will be averaged out.

Set the Vbus MAX voltage to the highest peak voltage expected. If using the sensor on the highside with voltage measuring, use 300 VDC range or lower.

A2D CONFIG default is: 0x035D.

Example: Vbus Max Voltage 1200 VDC, High Range 5X Nominal, Normal Range 1.25X Nominal, Reading Interval 820 ms (0x035D)

Write Message

	Message ID	Length	Data Fields								
SEND	0x3FA	0x03	0x17	0x03	0x5D						
RECEIVE		(none)									

Read Message

	Message ID	Length	Data Fields							
SEND	0x3FB	0x01	0x17							
RECEIVE	0x3FC	0x03	0x17	0x03	0x5D					

NOTE: No settings are saved until a save settings to EEPROM command is issued! Power cycling will restore previous settings. See command 0x10 0x000F.

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SSD Interface Manual (continued)

0x18 - Command CURRENT UNDER LIMIT - Read / Write

Used to configure the optional lower limit for current readings. Currents below this value will cause an error that can be read with the 0x07 GET ERRORS command if errors aren't automatically sent. A zero value disables this alert, non-zero values enable alert.

Value is a signed Int16 in amps. Default CURRENT UNDER LIMIT: 0x0000 (Disabled).

Example: Set the lower limit to 25 amps (0x0019)



Write Message

	Message ID	Length		Data Fields							
SEND	0x3FA	0x03	0x18	0x00	0x19						
RECEIVE		(none)									

Read Message

	Message ID	Length	Data Fields							
SEND	0x3FB	0x01	0x18							
RECEIVE	0x3FC	0x03	0x18	0x00	0x19					

NOTE: No settings are saved until a save settings to EEPROM command is issued! Power cycling will restore previous settings. See command 0x10 0x000F.

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SSD Interface Manual (continued)

0x19 - Command CURRENT OVER LIMIT - Read / Write

Used to configure the optional upper limit for current readings. Currents above this value will cause an error that can be read with the 0x07 GET ERRORS command if errors aren't automatically sent. A zero value disables this alert, non-zero values enable alert.

Value is a signed Int16 in amps. Default CURRENT OVER LIMIT: 0x0000 (Disabled).

Example: Set the upper limit to 620 amps (0x026C)



Write Message

	Message ID	Length		Data Fields					
SEND	0x3FA	0x03	0x19	0x02	0x6C				
RECEIVE		(none)							

Read Message

	Message ID	Length		Data Fields				
SEND	0x3FB	0x01	0x19					
RECEIVE	0x3FC	0x03	0x19	0x02	0x6C			

NOTE: No settings are saved until a save settings to EEPROM command is issued! Power cycling will restore previous settings. See command 0x10 0x000F.

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SSD Interface Manual (continued)

0x1A - Command TEMP OVER LIMIT - Read / Write

Used to configure the temperature limit for the error. Temperatures above this value will cause an error that can be read with the 0x07 GET ERRORS command if errors aren't automatically sent.

Value is an unsigned Int16 in centigrade. Default TEMP OVER LIMIT: 125 °C (0x007D, Cannot Disable)

Valid Range: 0 °C to +125 °C (MAX)

Example: Set the upper limit to 90 °C (0x005A)



Write Message

	Message ID	Length		Data Fields					
SEND	0x3FA	0x03	0x1A	0x02	0x5A				
RECEIVE		(none)							

Read Message

	Message ID	Length		Data Fields				
SEND	0x3FB	0x01	0x1A					
RECEIVE	0x3FC	0x03	0x1A	0x00	0x5A			

NOTE: No settings are saved until a save settings to EEPROM command is issued! Power cycling will restore previous settings. See command 0x10 0x000F.

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SSD Interface Manual (continued)

0x1B - Command VBUS UNDER LIMIT - Read / Write

Used to configure the optional lower limit for the bus voltage readings. Voltages below this value will cause an error that can be read with the 0x07 GET ERRORS command if errors aren't automatically sent. A zero value disables this alert, non-zero values enable alert.

Value is a signed Int16 in volts. Default VBUS UNDER LIMIT: 0x0000 (Disabled).

Example: Set the lower limit to 29 Volts (0x001D)



Write Message

	Message ID	Length		Data Fields						
SEND	0x3FA	0x03	0x1B	0x00	0x1D					
RECEIVE		(none)								

Read Message

	Message ID	Length		Data Fields				
SEND	0x3FB	0x01	0x1B					
RECEIVE	0x3FC	0x03	0x1B	0x00	0x1D			

NOTE: No settings are saved until a save settings to EEPROM command is issued! Power cycling will restore previous settings. See command 0x10 0x000F.

Specifications are subject to change without notice.

Users should verify actual device performance in their specific applications.

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SSD Interface Manual (continued)

0x1C - Command VBUS OVER LIMIT - Read / Write

Used to configure the optional upper limit for bus voltage readings. Voltages above this value will cause an error that can be read with the 0x07 GET ERRORS command if errors aren't automatically sent. A zero value disables this alert, non-zero values enable alert.

Value is a signed Int16 in Volts. Default VBUS OVER LIMIT: 0x0000 (Disabled).

Example: Set the upper limit to 70 Volts (0x0046)



Write Message

	Message ID	Length		Data Fields						
SEND	0x3FA	0x03	0x1C	0x00	0x46					
RECEIVE		(none)								

Read Message

	Message ID	Length		Data Fields				
SEND	0x3FB	0x01	0x1C					
RECEIVE	0x3FC	0x03	0x1C	0x00	0x46			

NOTE: No settings are saved until a save settings to EEPROM command is issued! Power cycling will restore previous settings. See command 0x10 0x000F.

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SSD Interface Manual (continued)

0x1D - Command POWER OVER LIMIT - Read / Write

Used to configure the optional upper limit for power readings. Power above this value will cause an error that can be read with the 0x07 GET ERRORS command if errors aren't automatically sent. A zero value disables this alert, non-zero values enable alert. Value is an unsigned Int32 in Watts. Default POWER OVER LIMIT: 0x00000000 (Disabled).

Example: Set the upper limit to 22000 Watts (0x000055F0)



Write Message

	Message ID	Length		Data Fields						
SEND	0x3FA	0x05	0x1D	0x00	0x00	0x55	0xF0			
RECEIVE	(none)									

Read Message

	Message ID	Length		Data Fields				
SEND	0x3FB	0x01	0x1D					
RECEIVE	0x3FC	0x05	0x1D	0x00	0x00	0x55	0xF0	

NOTE: No settings are saved until a save settings to EEPROM command is issued! Power cycling will restore previous settings. See command 0x10 0x000F.

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SSD Interface Manual (continued)

0x1E - Command SHUNT NANO-OHMS - Read / Write

Used to override the resistance of the Model SSD Series from the factory calibration. This is typically not necessary and the correct equipment is essential to properly set it. Value can be reset back to factory defaults.

Value is an Int32

Example: To set SHUNT NANO-OHMS to 300156 (0x0004947C) nano-ohms



Write Message

	Message ID	Length		Data Fields						
SEND	0x3FA	0x05	0x1E	0x00	0x04	0x94	0x7C			
RECEIVE	(none)									

Read Message

	Message ID	Length		Data Fields				
SEND	0x3FB	0x01	0x1E					
RECEIVE	0x3FC	0x05	0x1E	0x00	0x04	0x94	0x7C	

NOTE: No settings are saved until a save settings to EEPROM command is issued! Power cycling will restore previous settings. See command 0x10 0x000F.

Specifications are subject to change without notice.

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SSD Interface Manual (continued)

0x21 - Command CURRENT ZERO OFFSET - Read / Write

Used to override the sensor zero offset current. Value can be reset back to factory defaults.

Value is a signed Int16.

Example: To set CURRENT OFFSET to +8 (0x0008) mA.



Write Message

	Message ID	Length	Data Fields						
SEND	0x3FA	0x03	0x21	0x00	0x08				
RECEIVE		(none)							

Read Message

	Message ID	Length	Data Fields					
SEND	0x3FB	0x01	0x21					
RECEIVE	0x3FC	0x03	0x21	0x00	0x08			

NOTE: No settings are saved until a save settings to EEPROM command is issued! Power cycling will restore previous settings. See command 0x10 0x000F.

Specifications are subject to change without notice.

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SSD Interface Manual (continued)

0x22 - Command VBUS FACTOR - Read / Write

Used to adjust the Bus Voltage reading from the factory calibration. This is typically not necessary and the correct equipment is essential to properly set it. See reset command to set the value back to factory default. Voltage is calibrated at 25 °C. Power and Energy values are scaled appropriately.

Value is an Int16. Value is divided by 10000 in firmware to create the factor.

Example: To set VBUS FACTOR to 10023 (0x2727)



Write Message

	Message ID	Length		Data Fields						
SEND	0x3FA	0x03	0x22	0x27	0x27					
RECEIVE		(none)								

Read Message

	Message ID	Length	Data Fields					
SEND	0x3FB	0x01	0x22					
RECEIVE	0x3FC	0x03	0x22	0x27	0x27			

NOTE: No settings are saved until a save settings to EEPROM command is issued! Power cycling will restore previous settings. See command 0x10 0x000F.

Specifications are subject to change without notice.

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SSD Interface Manual (continued)

0x23 - Command VBUS ZERO OFFSET - Read / Write

Used to override the bus voltage zero offset. Value can be reset back to factory defaults.

Value is a signed Int16.

Example: To set VBUS OFFSET to -6 (0xFFF9) mV.



Write Message

	Message ID	Length	Data Fields						
SEND	0x3FA	0x03	0x23	0xFF	0xF9				
RECEIVE	(none)								

Read Message

	Message ID	Length	Data Fields					
SEND	0x3FB	0x01	0x23					
RECEIVE	0x3FC	0x03	0x23	0xFF	0xF9			

NOTE: No settings are saved until a save settings to EEPROM command is issued! Power cycling will restore previous settings. See command 0x10 0x000F.

Specifications are subject to change without notice.

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SSD Interface Manual (continued)

0x24 - Command TEMP OFFSET - Read / Write

Used to adjust the Temperature reading from the factory calibration. This is typically not necessary and the correct equipment is essential to properly set it. See reset command to set the value back to factory default. Value is an Signed Int16. Example: To set TEMP OFFSET to -2.2 °C send -22 (0xFFEA)



Write Message

	Message ID	Length	Data Fields						
SEND	0x3FA	0x03	0x24	0xFF	0xEA				
RECEIVE		(none)							

Read Message

	Message ID	Length	Data Fields					
SEND	0x3FB	0x01	0x24					
RECEIVE	0x3FC	0x03	0x24	0xFF	0xEA			

NOTE: No settings are saved until a save settings to EEPROM command is issued! Power cycling will restore previous settings. See command 0x10 0x000F.

Specifications are subject to change without notice.

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SSD Interface Manual (continued)

0x25 – Command GET T0 TEMPERATURE COMPENSATION – Read Only 0x26 – Command GET T1 TEMPERATURE COMPENSATION – Read Only 0x27 – Command GET T2 TEMPERATURE COMPENSATION – Read Only

Used to get the factory calibrated settings for the temperature compensation constants.

T0 - unsigned int16

T1 - signed int32

T2 - signed int32

Example: The following shows T1 compensation constant of FFBE E23D (-4267459)

Read Message

	Message ID	Length	Data Fields					
SEND	0x3FB	0x01	0x26					
RECEIVE	0x3FC	0x05	0x26	0xFF	0xBE	0xE2	0x3D	

NOTE: No settings are saved until a save settings to EEPROM command is issued! Power cycling will restore previous settings. See command 0x10 0x000F.

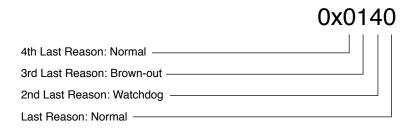
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SSD Interface Manual (continued)

0x28 – Command GET RESET CAUSES – Read Only Used to get the reasons for the last four SSD sensor restarts. Example: The following shows abnormal restarts (0x0140)

Read Message

	Message ID	Length	Data Fields					
SEND	0x3FB	0x01	0x28					
RECEIVE	0x3FC	0x03	0x28	0x01	0x40			



Reason Codes

- 0 Normal Power-on Reset
- 1 Brown-out Reset
- 4 Watchdog Timer Time-Out Reset
- 6 Software RESET Instruction
- 7 Master Clear Pin Reset
- 9 Configuration Mismatch Reset
- E Illegal Condition Device Reset
 - Illegal Opcode Reset
 - Uninitialized W Register Reset
 - Security Reset
- F Trap Conflict Reset

Specifications are subject to change without notice.

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Users should verify actual device performance in their specific applications.
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SSD Interface Manual (continued)

0x30 – Command GET FIRMWARE VERSION – Read Only Used to get the SSD firmware version. Data Returned: Version (byte) and subversion (byte) Example: The following shows version (v1.2)

Read Message

	Message ID	Length	Data Fields					
SEND	0x3FB	0x01	0x30					
RECEIVE	0x3FC	0x03	0x30	0x01	0x02			

0x31 – Command GET SERIAL NUMBER – Read Only Used to get the SSD serial number. Example: The following shows SN:00012345 (0x3039)

Read Message

	Message ID	Length	Data Fields					
SEND	0x3FB	0x01	0x31					
RECEIVE	0x3FC	0x05	0x31	0x00	0x00	0x30	0x39	

NOTE: No settings are saved until a save settings to EEPROM command is issued! Power cycling will restore previous settings. See command 0x10 0x000F.

Users should verify actual device performance in their specific applications.

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SSD Interface Manual (continued)

Firmware Revisions-

v2.10

Added Invert Bus Voltage bit to SETMODE command for highside sensor mounting.

v2.11

Updated internal ADC settings to reduce noise. This reduces some of the fixed ADC reading intervals.

Fixed reading Coulombs and Energy manually after changing CAN IDs.

v2.12

Bus Voltage is now signed int32, ±1200 VDC.

Current and Voltage Under and Over limits are now signed int16.

Can now write Coulomb value to sensor and the sensor will count from there.

Get all enabled readings changed from register 0x08 to 0x00.

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